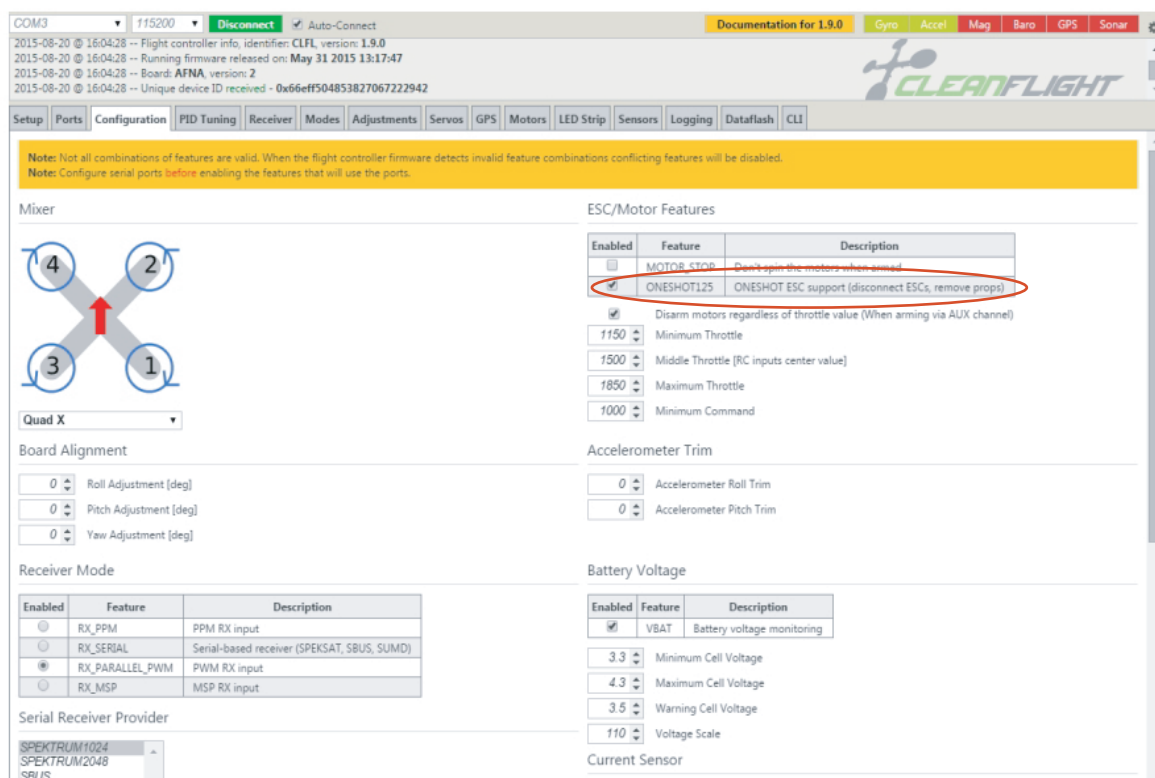


# OneShot125 設定方法



Note: Not all combinations of features are valid. When the flight controller firmware detects invalid feature combinations conflicting features will be disabled.  
Note: Configure serial ports before enabling the features that will use the ports.

Mixer

ESC/Motor Features

Enabled	Feature	Description
<input type="checkbox"/>	MOTOR_STOP	Disconnect motors when armed
<input checked="" type="checkbox"/>	ONESHOT125	ONESHOT ESC support (disconnect ESCs, remove props)
<input checked="" type="checkbox"/>		Disarm motors regardless of throttle value (When arming via AUX channel)
1150		Minimum Throttle
1500		Middle Throttle [RC inputs center value]
1850		Maximum Throttle
1000		Minimum Command

Accelerometer Trim

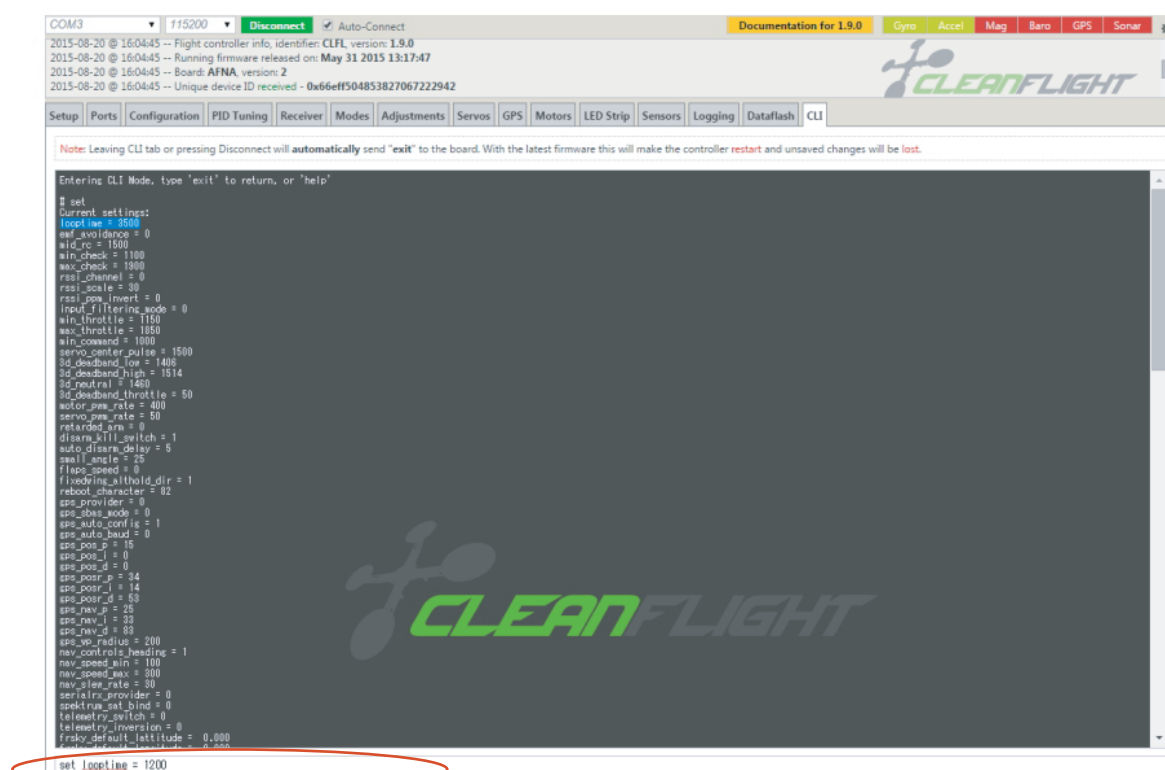
0	Accelerometer Roll Trim
0	Accelerometer Pitch Trim

Battery Voltage

Enabled	Feature	Description
<input checked="" type="checkbox"/>	VBAT	Battery voltage monitoring
3.3		Minimum Cell Voltage
4.3		Maximum Cell Voltage
3.5		Warning Cell Voltage
110		Voltage Scale

Current Sensor

丸の項目にチェックを入れてSAVEします。



Note: Leaving CLI tab or pressing Disconnect will automatically send "exit" to the board. With the latest firmware this will make the controller restart and unsaved changes will be lost.

```
Entering CLI Mode, type 'exit' to return, or 'help'
# set
Current settings:
looptime = 2500
sw_aidelay = 0
wid_rc = 1500
win_check = 1100
wsc_check = 1300
rsi_channel = 0
rsi_scale = 90
rsi_pos_invert = 0
input_filtering_mode = 0
win_throttle = 1150
wsc_throttle = 1500
win_command = 1000
servo_center_pulse = 1500
3d_deadband_low = 1405
3d_deadband_high = 1514
3d_neutral = 1451
3d_deadband_throttle = 50
motor_pwm_rate = 400
servo_pwm_rate = 50
retarded_arm = 0
disarm_kill_switch = 1
auto_disarm_delay = 5
roll_angle = 25
flaps_speed = 0
flapping_threshold_dir = 1
reboot_character = 02
sps_provider = 0
sps_sbas_mode = 0
sps_auto_config = 1
sps_auto_baud = 0
sps_pos_p = 15
sps_pos_i = 0
sps_pos_d = 0
sps_posr_p = 34
sps_posr_i = 14
sps_posr_d = 53
sps_nav_p = 25
sps_nav_i = 35
sps_nav_d = 93
sps_wp_radius = 200
nav_control_mode = heading = 1
nav_speed_min = 100
nav_speed_max = 200
nav_climb_rate = 30
serial_provider = 0
spektrum_sst_bind = 0
telemetry_switch = 0
telemetry_inversion = 0
frsky_default_latitude = 0.000

set looptime = 1200
```

1. CLIの項目で丸の部分に set looptime = 1200を記入後エンターを押します。
2. saveを記入しエンターを押します。

完了

※設定は、CleanFlight設定ソフトをご使用ください。